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Lecture 1 Basic definitions

## Definition 1.1

A knot $K$ in $S^{3}$ is a smooth (PL - smooth) embedding of a circle $S^{1}$ in $S^{3}$ :

$$
\varphi: S^{1} \hookrightarrow S^{3}
$$

Usually we think about a knot as an image of an embedding: $K=\varphi\left(S^{1}\right)$.
Example 1.1

- Knots:

- Not knots:
 (it is not an injection),
 (it is not smooth).


## Definition 1.2

Two knots $K_{0}=\varphi_{0}\left(S^{1}\right), K_{1}=\varphi_{1}\left(S^{1}\right)$ are equivalent if the embeddings $\varphi_{0}$ and $\varphi_{1}$ are isotopic, that is there exists a continues function

$$
\begin{aligned}
& \Phi: S^{1} \times[0,1] \hookrightarrow S^{3} \\
& \Phi(x, t)=\Phi_{t}(x)
\end{aligned}
$$

such that $\Phi_{t}$ is an embedding for any $t \in[0,1], \Phi_{0}=\varphi_{0}$ and $\Phi_{1}=\varphi_{1}$.

## Theorem 1.1

Two knots $K_{0}$ and $K_{1}$ are isotopic if and only if they are ambient isotopic, i.e. there exists a family of self-diffeomorphisms $\Psi=\left\{\psi_{t}: t \in[0,1]\right\}$ such that:

$$
\begin{aligned}
& \psi(t)=\psi_{t} \text { is continius on } t \in[0,1] \\
& \psi_{t}: S^{3} \hookrightarrow S^{3} \\
& \psi_{0}=i d \\
& \psi_{1}\left(K_{0}\right)=K_{1}
\end{aligned}
$$

## Definition 1.3

A knot is trivial (unknot) if it is equivalent to an embedding $\varphi(t)=(\cos t, \sin t, 0)$, where $t \in[0,2 \pi]$ is a parametrisation of $S^{1}$.

## Definition 1.4

A link with $k$-components is a (smooth) embedding of $\overbrace{S^{1} \sqcup \ldots \sqcup S^{1}}^{k}$ in $S^{3}$

## Example 1.2

Links:

- a trivial link with 3 components:

- a hopf link:

- a Whitehead link:

- Borromean link:



## Definition 1.5

A link diagram $D_{\pi}$ is a picture over projection $\pi$ of a link $L$ in $\mathbb{R}^{3}\left(S^{3}\right)$ to $\mathbb{R}^{2}$ ( $S^{2}$ ) such that:
(1) $D_{\left.\pi\right|_{L}}$ is non degenerate:

(2) the double points are not degenerate: $/$
(3) there are no triple point: $\nless$

There are under- and overcrossings (tunnels and bridges) on a link diagrams with an obvious meaning.
Every link admits a link diagram.
Let $D$ be a diagram of an oriented link (to each component of a link we add an arrow in the diagram).
We can distinguish two types of crossings: right-handed ( $\times$ ), called a positive crossing, and left-handed $\left(\lambda^{\wedge}\right)$, called a negative crossing.

### 1.1 Reidemeister moves

A Reidemeister move is one of the three types of operation on a link diagram as shown below:
I




Theorem 1.2 (Reidemeister, 1927 )
Two diagrams of the same link can be deformed into each other by a finite sequence of Reidemeister moves (and isotopy of the plane).

### 1.2 Seifert surface

Let $D$ be an oriented diagram of a link $L$. We change the diagram by smoothing each crossing:

$$
\begin{aligned}
& x \mapsto)( \\
& x \mapsto)(
\end{aligned}
$$

We smooth all the crossings, so we get a disjoint union of circles on the plane. Each circle bounds a disks in $\mathbb{R}^{3}$ (we choose disks that don't intersect). For each smoothed crossing we add a twisted band: right-handed for a positive and left-handed for a negative one. We get an orientable surface $\Sigma$ such that $\partial \Sigma=L$.


Figure 1: Constructing a Seifert surface.

Note: the obtained surface isn't unique and in general doesn't need to be connected, but by taking connected sum of all components we can easily get a connected surface (i.e. we take two disconnected components and cut a disk in each of them: $D_{1}$ and $D_{2}$; now we glue both components on the boundaries: $\partial D_{1}$ and $\partial D_{2}$.

Theorem 1.3 (Seifert)
Every link in $S^{3}$ bounds a surface $\Sigma$ that is compact, connected and orientable. Such a surface is called a Seifert surface.

## Definition 1.6

The three genus $g_{3}(K)(g(K))$ of a knot $K$ is the minimal genus of a Seifert surface $\Sigma$ for $K$.

## Corollary 1.1

$A$ knot $K$ is trivial if and only $g_{3}(K)=0$.


Figure 2: Connecting two surfaces.


Figure 3: Genus of an orientable surface.

Remark: there are knots that admit non isotopic Seifert surfaces of minimal genus (András Juhász, 2008).

## Definition 1.7

Suppose $\alpha$ and $\beta$ are two simple closed curves in $\mathbb{R}^{3}$. On a diagram $L$ consider all crossings between $\alpha$ and $\beta$. Let $N_{+}$be the number of positive crossings, $N_{-}-$negative. Then the linking number: $\operatorname{lk}(\alpha, \beta)=\frac{1}{2}\left(N_{+}-N_{-}\right)$.

Let $\alpha$ and $\beta$ be two disjoint simple cross curves in $S^{3}$. Let $\nu(\beta)$ be a tubular neighbourhood of $\beta$. The linking number can be interpreted via first homology group, where $\operatorname{lk}(\alpha, \beta)$ is equal to evaluation of $\alpha$ as element of first
homology group of the complement of $\beta$ :

$$
\alpha \in H_{1}\left(S^{3} \backslash \nu(\beta), \mathbb{Z}\right) \cong \mathbb{Z}
$$

## Example 1.3

- Hopf link:

- $T(6,2)$ link:



## Fact 1.1

$$
g_{3}(\Sigma)=\frac{1}{2} b_{1}(\Sigma)=\frac{1}{2} \operatorname{dim}_{\mathbb{R}} H_{1}(\Sigma, \mathbb{R}),
$$

where $b_{1}$ is first Betti number of $\Sigma$.

### 1.3 Seifert matrix

Let $L$ be a link and $\Sigma$ be an oriented Seifert surface for $L$. Choose a basis for $H_{1}(\Sigma, \mathbb{Z})$ consisting of simple closed $\alpha_{1}, \ldots, \alpha_{n}$. Let $\alpha_{1}^{+}, \ldots \alpha_{n}^{+}$be copies of $\alpha_{i}$ lifted up off the surface (push up along a vector field normal to $\Sigma$ ). Note that elements $\alpha_{i}$ are contained in the Seifert surface while all $\alpha_{i}^{+}$are don't intersect the surface. Let $\operatorname{lk}\left(\alpha_{i}, \alpha_{j}^{+}\right)=\left\{a_{i j}\right\}$. Then the matrix $S=\left\{a_{i j}\right\}_{i, j=1}^{n}$ is called a Seifert matrix for $L$. Note that by choosing a different basis we get a different matrix.


## Theorem 1.4

The Seifert matrices $S_{1}$ and $S_{2}$ for the same link $L$ are $S$-equivalent, that is, $S_{2}$ can be obtained from $S_{1}$ by a sequence of following moves:
(1) $V \rightarrow A V A^{T}$, where $A$ is a matrix with integer coefficients,
(2) $V \rightarrow\left(\begin{array}{ccc|cc} & & & * & 0 \\ \vdots & & \vdots \\ \vdots & & & * & 0 \\ \hline * & \ldots & * & 0 & 0 \\ 0 & \ldots & 0 & 1 & 0\end{array}\right) \quad$ or $\quad V \rightarrow\left(\begin{array}{ccc|cc} & & & * & 0 \\ & V & & \vdots & \vdots \\ & & & * & 0 \\ \hline * & \ldots & * & 0 & 1 \\ 0 & \ldots & 0 & 0 & 0\end{array}\right)$
(3) inverse of (2)

## Lecture 2

March 4, 2019

## Theorem 2.1

For any knot $K \subset S^{3}$ there exists a connected, compact and orientable surface $\Sigma(K)$ such that $\partial \Sigma(K)=K$
Proof. ("joke")
Let $K \in S^{3}$ be a knot and $N=\nu(K)$ be its tubular neighbourhood. Because $K$ and $N$ are homotopy equivalent, we get:

$$
H^{1}\left(S^{3} \backslash N\right) \cong H^{1}\left(S^{3} \backslash K\right)
$$

Let us consider a long exact sequence of cohomology of a pair $\left(S^{3}, S^{3} \backslash N\right)$ with integer coefficients:

$$
\begin{aligned}
& \mathbb{Z} \\
& 211 \\
& H^{0}\left(S^{3}\right) \rightarrow H^{0}\left(S^{3} \backslash N\right) \rightarrow \\
& \rightarrow H^{1}\left(S^{3}, S^{3} \backslash N\right) \rightarrow \underset{\text { H }}{\text { 1 }}\left(S^{3}\right) \rightarrow \quad H^{1}\left(S^{3} \backslash N\right) \rightarrow \\
& 0 \\
& 21 \\
& \rightarrow H^{2}\left(S^{3}, S^{3} \backslash N\right) \rightarrow H^{2}\left(S^{3}\right) \rightarrow H^{2}\left(S^{3} \backslash N\right) \rightarrow \\
& \rightarrow H^{3}\left(S^{3}, S^{3} \backslash N\right) \rightarrow \quad H^{3}(S) \rightarrow \quad 0 \\
& 21 \\
& \mathbb{Z} \\
& H^{*}\left(S^{3}, S^{3} \backslash N\right) \cong H^{*}(N, \partial N)
\end{aligned}
$$

??????????????

## Definition 2.1

Let $S$ be a Seifert matrix for a knot $K$. The Alexander polynomial $\Delta_{K}(t)$ is a Laurent polynomial:

$$
\Delta_{K}(t):=\operatorname{det}\left(t S-S^{T}\right) \in \mathbb{Z}\left[t, t^{-1}\right] \cong \mathbb{Z}[\mathbb{Z}]
$$

## Theorem 2.2

$\Delta_{K}(t)$ is well defined up to multiplication by $\pm t^{k}$, for $k \in \mathbb{Z}$.
Proof. We need to show that $\Delta_{K}(t)$ doesn't depend on $S$-equivalence relation.
(1) Suppose $S^{\prime}=C S C^{T}, C \in \operatorname{GL}(n, \mathbb{Z})$ (matrices invertible over $\mathbb{Z}$ ). Then $\operatorname{det} C=1$ and:

$$
\begin{aligned}
& \operatorname{det}\left(t S^{\prime}-S^{\prime T}\right)=\operatorname{det}\left(t C S C^{T}-\left(C S C^{T}\right)^{T}\right)= \\
& \operatorname{det}\left(t C S C^{T}-C S^{T} C^{T}\right)=\operatorname{det} C\left(t S-S^{T}\right) C^{T}=\operatorname{det}\left(t S-S^{T}\right)
\end{aligned}
$$

(2) Let

$$
A:=t\left(\begin{array}{ccc|cc} 
& & & * & 0 \\
& S & & \vdots & \vdots \\
& & * & 0 \\
\hline * & \ldots & * & 0 & 0 \\
0 & \ldots & 0 & 1 & 0
\end{array}\right)-\left(\begin{array}{ccc|cc} 
& & & * & 0 \\
& S^{T} & & \vdots & \vdots \\
& & & * & 0 \\
\hline * & \ldots & * & 0 & 1 \\
0 & \ldots & 0 & 0 & 0
\end{array}\right)=\left(\begin{array}{ccc|cc}
t S & -S^{T} & * & 0 \\
& & \vdots \\
& & & 0 \\
\hline * & \ldots & * & 0 & -1 \\
0 & \ldots & 0 & t & 0
\end{array}\right)
$$

Using the Laplace expansion we get $\operatorname{det} A= \pm t \operatorname{det}\left(t S-S^{T}\right)$.

## Example 2.1

If $K$ is a trefoil then we can take $S=\left(\begin{array}{cc}-1 & -1 \\ 0 & -1\end{array}\right)$. Then
$\Delta_{K}(t)=\operatorname{det}\left(\begin{array}{cc}-t+1 & -t \\ 1 & -t+1\end{array}\right)=(t-1)^{2}+t=t^{2}-t+1 \neq 1 \Rightarrow$ trefoil is not trivial.
Fact 2.1
$\Delta_{K}(t)$ is symmetric.
Proof. Let $S$ be an $n \times n$ matrix.

$$
\begin{aligned}
& \Delta_{K}\left(t^{-1}\right)=\operatorname{det}\left(t^{-1} S-S^{T}\right)=(-t)^{-n} \operatorname{det}\left(t S^{T}-S\right)= \\
& (-t)^{-n} \operatorname{det}\left(t S-S^{T}\right)=(-t)^{-n} \Delta_{K}(t)
\end{aligned}
$$

If $K$ is a knot, then $n$ is necessarily even, and so $\Delta_{K}\left(t^{-1}\right)=t^{-n} \Delta_{K}(t)$.

## Lemma 2.1

$$
\frac{1}{2} \operatorname{deg} \Delta_{K}(t) \leq g_{3}(K), \text { where } \operatorname{deg}\left(a_{n} t^{n}+\cdots+a_{1} t^{l}\right)=k-l
$$

Proof. If $\Sigma$ is a genus $g$ - Seifert surface for $K$ then $H_{1}(\Sigma)=\mathbb{Z}^{2 g}$, so $S$ is an $2 g \times 2 g$ matrix. Therefore $\operatorname{det}\left(t S-S^{T}\right)$ is a polynomial of degree at most $2 g$.

## Example 2.2

There are not trivial knots with Alexander polynomial equal 1, for example:


Lemma 2.2 (Dehn)
Let $M$ be a 3-manifold and $D^{2} \xrightarrow{f} M^{3}$ be a map of a disk such that $f_{\mid \partial D^{2}}$ is an embedding. Then there exists an embedding $D^{2} \stackrel{g}{\hookrightarrow} M$ such that:

$$
g_{\mid \partial D^{2}}=f_{\mid \partial D^{2}}
$$

## Lecture 3

## Example 3.1

$$
\begin{aligned}
& F: \mathbb{C}^{2} \rightarrow \mathbb{C} \text { a polynomial } \\
& F(0)=0
\end{aligned}
$$

????????????
as a corollary we see that $K_{T}^{n,}$ ????
is not slice unless $m=0$.

## Theorem 3.1

The map $j: \mathcal{C} \longrightarrow \mathbb{Z}^{\infty}$ is a surjection that maps $K_{n}$ to a linear independent set. Moreover $\mathcal{C} \cong \mathbb{Z}$

Fact 3.1 (Milnor Singular Points of Complex Hypersurfaces)

An oriented knot is called negative amphichiral if the mirror image $m(K)$ of $K$ is equivalent the reverse knot of $K: K^{r}$.

## Problem 3.1

Prove that if $K$ is negative amphichiral, then $K \# K=0$ in $\mathcal{C}$.

## Example 3.2

Figure 8 knot is negative amphichiral.

Lecture 4 Concordance group
March 18, 2019

## Definition 4.1

Two knots $K$ and $K^{\prime}$ are called (smoothly) concordant if there exists an annulus $A$ that is smoothly embedded in $S^{3} \times[0,1]$ such that

$$
\partial A=K^{\prime} \times\{1\} \sqcup K \times\{0\} .
$$



## Definition 4.2

A knot $K$ is called (smoothly) slice if $K$ is smoothly concordant to an unknot. $A$ knot $K$ is smoothly slice if and only if $K$ bounds a smoothly embedded disk in $B^{4}$.

Let $m(K)$ denote a mirror image of a knot $K$.

## Fact 4.1

For any $K, K \# m(K)$ is slice.

## Fact 4.2

Concordance is an equivalence relation.
Fact 4.3
If $K_{1} \sim K_{1}{ }^{\prime}$ and $K_{2} \sim K_{2}{ }^{\prime}$, then $K_{1} \# K_{2} \sim K_{1}{ }^{\prime} \# K_{2}{ }^{\prime}$.


Figure 4: Sketch for Fakt 4.3.

## Fact 4.4

$K \# m(K) \sim$ the unknot.

## Theorem 4.1

Let $\mathcal{C}$ denote a set of all equivalent classes for knots and $\{0\}$ denote class of all knots concordant to a trivial knot. $\mathcal{C}$ is a group under taking connected sums. The neutral element in the group is $\{0\}$ and the inverse element of an element $\{K\} \in \mathcal{C}$ is $-\{K\}=\{m K\}$.

## Fact 4.5

The figure eight knot is a torsion element in $\mathcal{C}$ ( $2 K \sim$ the unknot).
Problem 4.1 (open)
Are there in concordance group torsion elements that are not 2 torsion elements?

Remark: $K \sim K^{\prime} \Leftrightarrow K \#-K^{\prime}$ is slice.
Let $\Omega$ be an oriented four-manifold.
???????
Suppose $\Sigma$ is a Seifert surface and $V$ a Seifert form defined on $\Sigma:(\alpha, \beta) \mapsto \operatorname{lk}\left(\alpha, \beta^{+}\right)$.
Suppose $\alpha, \beta \in H_{1}(\Sigma, \mathbb{Z})$ (i.e. there are cycles).
??????????????
$\alpha, \beta \in \operatorname{ker}\left(H_{1}(\Sigma, \mathbb{Z}) \longrightarrow H_{1}(\Omega, \mathbb{Z})\right)$. Then there are two cycles $A, B \in \Omega$ such that $\partial A=\alpha$ and $\partial B=\beta$. Let $B^{+}$be a push off of $B$ in the positive normal direction such that $\partial B^{+}=\beta^{+}$. Then $\operatorname{lk}\left(\alpha, \beta^{+}\right)=A \cdot B^{+}$

Lecture 5
April 8, 2019
$X$ is a closed orientable four-manifold. Assume $\pi_{1}(X)=0$ (it is not needed to define the intersection form). In particular $H_{1}(X)=0 . H_{2}$ is free (exercise).

$$
H_{2}(X, \mathbb{Z}) \xrightarrow{\text { Poincaré duality }} H^{2}(X, \mathbb{Z}) \xrightarrow{\text { evaluation }} \operatorname{Hom}\left(H_{2}(X, \mathbb{Z}), \mathbb{Z}\right)
$$

Intersection form: $H_{2}(X, \mathbb{Z}) \times H_{2}(X, \mathbb{Z}) \longrightarrow \mathbb{Z}$ - symmetric, non singular. Let $A$ and $B$ be closed, oriented surfaces in $X$.

## Proposition 5.1

$A \cdot B$ doesn't depend of choice of $A$ and $B$ in their homology classes.

Lecture 6
March 11, 2019

## Definition 6.1

A link $L$ is fibered if there exists a map $\phi: S^{3} \backslash L \longleftarrow S^{1}$ which is locally trivial fibration.

## Lecture 7

April 15, 2019

In other words:
Choose a basis $\left(b_{1}, \ldots, b_{i}\right)$
???
of $H_{2}\left(Y, \mathbb{Z}\right.$, then $A=\left(b_{i}, b_{y}\right)$
??
is a matrix of intersection form:

$$
\mathbb{Z}^{n} /_{A \mathbb{Z}^{n}} \cong H_{1}(Y, \mathbb{Z})
$$

In particular $|\operatorname{det} A|=\# H_{1}(Y, \mathbb{Z})$.
That means - what is happening on boundary is a measure of degeneracy.

$$
\begin{array}{cc}
H_{1}(Y, \mathbb{Z}) & \times H_{1}(Y, \mathbb{Z}) \\
\text { 2\| } & \longrightarrow \\
\mathbb{Z}^{n} / A \mathbb{Q} / \mathbb{Z}^{\text {2 }} \text { - a linking form } \\
& \mathbb{Z}^{n} / A \mathbb{Z} \\
& (a, b) \mapsto a A^{-1} b^{T}
\end{array}
$$

?????????????????????????????????
The intersection form on a four-manifold determines the linking on the boundary.

Let $K \in S^{1}$ be a knot, $\Sigma(K)$ its double branched cover. If $V$ is a Seifert matrix for $K$, then $H_{1}(\Sigma(K), \mathbb{Z}) \cong \mathbb{Z}^{n} / A \mathbb{Z}$ where $A=V \times V^{T}, n=\operatorname{rank} V$. Let $X$ be the four-manifold obtained via the double branched cover of $B^{4}$


Figure 5: Pushing the Seifert surface in 4-ball.
branched along $\widetilde{\Sigma}$.

## Fact 7.1

- $X$ is a smooth four-manifold,
- $H_{1}(X, \mathbb{Z})=0$,
- $H_{2}(X, \mathbb{Z}) \cong \mathbb{Z}^{n}$
- The intersection form on $X$ is $V+V^{T}$.


Figure 6: Cycle pushed in 4-ball.
Let $Y=\Sigma(K)$. Then:

$$
\begin{aligned}
H_{1}(Y, \mathbb{Z}) \times H_{1}(Y, \mathbb{Z}) & \longrightarrow \mathbb{Q} / \mathbb{Z} \\
(a, b) & \mapsto a A^{-1} b^{T}, \quad A=V+V^{T}
\end{aligned}
$$

????????????????????????????

$$
\begin{aligned}
& H_{1}(Y, \mathbb{Z}) \cong \mathbb{Z}^{n} / A \mathbb{Z} \\
A \longrightarrow B A C^{T} & \text { Smith normal form }
\end{aligned}
$$

???????????????????????
In general

Lecture 8
May 20, 2019

Let $M$ be compact, oriented, connected four-dimensional manifold. If $H_{1}(M, \mathbb{Z})=0$ then there exists a bilinear form - the intersection form on $M$ :

$$
\begin{aligned}
& \underset{2 \|}{H_{2}(M, \mathbb{Z})} \quad \times \quad H_{2}(M, \mathbb{Z}) \longrightarrow \quad \mathbb{Z} \\
& \quad \mathbb{Z}^{n}
\end{aligned}
$$

Let us consider a specific case: $M$ has a boundary $Y=\partial M$. Betti number $b_{1}(Y)=0, H_{1}(Y, \mathbb{Z})$ is finite. Then the intersection form can be degenerated in the sense that:

$$
\begin{array}{rlrl}
H_{2}(M, \mathbb{Z}) \times H_{2}(M, \mathbb{Z}) & \longrightarrow \mathbb{Z} & H_{2}(M, \mathbb{Z}) & \longrightarrow \operatorname{Hom}\left(H_{2}(M, \mathbb{Z}), \mathbb{Z}\right) \\
(a, b) & \mapsto \mathbb{Z} & a & \mapsto\left(a, \_\right) H_{2}(M, \mathbb{Z})
\end{array}
$$

has coker precisely $H_{1}(Y, \mathbb{Z})$.
???????????????
Let $K \subset S^{3}$ be a knot, $X=S^{3} \backslash K$ - a knot complement, $\widetilde{X} \xrightarrow{\rho} X$ - an infinite cyclic cover (universal abelian cover).

$$
\pi_{1}(X) \longrightarrow \pi_{1}(X) /\left[\pi_{1}(X), \pi_{1}(X)\right]=H_{1}(X, \mathbb{Z}) \cong \mathbb{Z}
$$

$C_{*}(\widetilde{X})$ has a structure of a $\mathbb{Z}\left[t, t^{-1}\right] \cong \mathbb{Z}[\mathbb{Z}]$ module.
$H_{1}\left(\widetilde{X}, \mathbb{Z}\left[t, t^{-1}\right]\right)$ - Alexander module,

$$
H_{1}\left(\widetilde{X}, \mathbb{Z}\left[t, t^{-1}\right]\right) \times H_{1}\left(\widetilde{X}, \mathbb{Z}\left[t, t^{-1}\right]\right) \longrightarrow \mathbb{Q} / \mathbb{Z}\left[t, t^{-1}\right]
$$

## Fact 8.1

$$
H_{1}\left(\widetilde{X}, \mathbb{Z}\left[t, t^{-1}\right]\right) \cong \mathbb{Z}\left[t, t^{-1}\right]^{n} /\left(t V-V^{T}\right) \mathbb{Z}\left[t, t^{-1}\right]^{n}
$$

where $V$ is a Seifert matrix.

## Fact 8.2

$$
\begin{aligned}
H_{1}\left(\widetilde{X}, \mathbb{Z}\left[t, t^{-1}\right]\right) \times H_{1}\left(\widetilde{X}, \mathbb{Z}\left[t, t^{-1}\right]\right) & \longrightarrow \mathbb{Q} / \mathbb{Z}\left[t, t^{-1}\right] \\
(\alpha, \beta) & \mapsto \alpha^{-1}(t-1)\left(t V-V^{T}\right)^{-1} \beta
\end{aligned}
$$

Note that $\mathbb{Z}$ is not PID. Therefore we don't have primer decomposition of this moduli. We can simplify this problem by replacing $\mathbb{Z}$ by $\mathbb{R}$. We lose some date by doing this transition.

$$
\begin{aligned}
& \xi \in S^{1} \backslash\{ \pm 1\} \quad p_{\xi}=(t-\xi)\left(t-\xi^{-1}\right) t^{-1} \\
& \xi \in \mathbb{R} \backslash\{ \pm 1\} \quad q_{\xi}=(t-\xi)\left(t-\xi^{-1}\right) t^{-1} \\
& \xi \notin \mathbb{R} \cup S^{1} \quad q_{\xi}=(t-\xi)(t-\bar{\xi})\left(t-\xi^{-1}\right)\left(t-\bar{\xi}^{-1}\right) t^{-2} \\
& \Lambda=\mathbb{R}\left[t, t^{-1}\right] \\
& \text { Then: } H_{1}(\widetilde{X}, \Lambda) \cong \bigoplus_{\xi \in S^{1} \backslash\{ \pm 1\}}^{k \geq 0}< \\
& \left(\Lambda / p_{\xi}^{k}\right)^{n_{k}, \xi} \oplus \bigoplus_{\substack{\xi \notin S^{1} \\
l \geq 0}}\left(\Lambda / q_{\xi}^{l} n^{n_{l}, \xi}\right.
\end{aligned}
$$

We can make this composition orthogonal with respect to the Blanchfield paring.

Historical remark:

- John Milnor, On isometries of inner product spaces, 1969,
- Walter Neumann, Invariants of plane curve singularities, 1983,
- András Némethi, The real Seifert form and the spectral pairs of isolated hypersurfaceenumerate singularities, 1995,
- Maciej Borodzik, Stefan Friedl The unknotting number and classical invariants II, 2014.

Let $p=p_{\xi}, k \geq 0$.

$$
\begin{aligned}
\Lambda / p^{k} \Lambda \times \Lambda / p^{k} \Lambda & \longrightarrow \mathbb{Q}(t) / \Lambda \\
(1,1) & \mapsto \kappa \\
\text { Now: }\left(p^{k} \cdot 1,1\right) & \mapsto 0 \\
p^{k} \kappa=0 & \in \mathbb{Q}(t) / \Lambda \\
\text { therfore } p^{k} \kappa & \in \Lambda \\
\text { we have }(1,1) & \mapsto \frac{h}{p^{k}}
\end{aligned}
$$

$h$ is not uniquely defined: $h \rightarrow h+g p^{k}$ doesn't affect paring.
Let $h=p^{k} \kappa$.

## Example 8.1

$$
\begin{aligned}
& \phi_{0}((1,1))=\frac{+1}{p} \\
& \phi_{1}((1,1))=\frac{-1}{p}
\end{aligned}
$$

$\phi_{0}$ and $\phi_{1}$ are not isomorphic.
Proof. Let $\Phi: \Lambda / p^{k} \Lambda \longrightarrow \Lambda / p^{k} \Lambda$ be an isomorphism.
Let: $\Phi(1)=g \in \lambda$

$$
\begin{gathered}
\Lambda / p^{k} \Lambda \xrightarrow{\Phi} \Lambda / p^{k} \Lambda \\
\phi_{0}((1,1))=\frac{1}{p^{k}} \quad \phi_{1}((g, g))=\frac{1}{p^{k}} \quad(\Phi \text { is an isometry }) .
\end{gathered}
$$

Suppose for the paring $\phi_{1}((g, g))=\frac{1}{p^{k}}$ we have $\phi_{1}((1,1))=\frac{-1}{p^{k}}$. Then:

$$
\begin{aligned}
\frac{-g \bar{g}}{p^{k}}=\frac{1}{p^{k}} & \in \mathbb{Q}(t) / \Lambda \\
\frac{-g \bar{g}}{p^{k}}-\frac{1}{p^{k}} & \in \Lambda \\
-g \bar{g} & \equiv 1 \quad(\bmod p) \text { in } \Lambda \\
-g \bar{g}-1 & =p^{k} \omega \text { for some } \omega \in \Lambda
\end{aligned}
$$

evalueting at $\xi$ :

$$
\overbrace{-g(\xi) g\left(\xi^{-1}\right)}^{>0}-1=0 \quad \Rightarrow \Leftarrow
$$

????????????????????

$$
\begin{aligned}
g & =\sum g_{i} t^{i} \\
\bar{g} & =\sum g_{i} t^{-i} \\
\bar{g}(\xi) & =\sum g_{i} \xi^{i} \quad \xi \in S^{1} \\
\bar{g}(\xi) & =g(\bar{\xi})
\end{aligned}
$$

Suppose $g=(t-\xi)^{\alpha} g^{\prime}$. Then $(t-\xi)^{k-\alpha}$ goes to 0 in $\Lambda / p^{k} \Lambda$.

## Theorem 8.1

Every sesquilinear non-degenerate pairing

$$
\Lambda / p^{k} \times \Lambda / p \leftrightarrow \frac{h}{p^{k}}
$$

is isomorphic either to the pairing wit $h=1$ or to the paring with $h=-1$ depending on sign of $h(\xi)$ (which is a real number).

Proof. There are two steps of the proof:

1. Reduce to the case when $h$ has a constant sign on $S^{1}$.
2. Prove in the case, when $h$ has a constant sign on $S^{1}$.

## Lemma 8.1

If $P$ is a symmetric polynomial such that $P(\eta) \geq 0$ for all $\eta \in S^{1}$, then $P$ can be written as a product $P=g \bar{g}$ for some polynomial $g$.

Sketch of proof. Induction over $\operatorname{deg} P$.
Let $\zeta \notin S^{1}$ be a root of $P, P \in \mathbb{R}\left[t, t^{-1}\right]$. Assume $\zeta \notin \mathbb{R}$. We know that polynomial $P$ is divisible by $(t-\zeta),(t-\bar{\zeta}),\left(t^{-1}-\zeta\right)$ and $\left(t^{-1}-\bar{\zeta}\right)$. Therefore:

$$
\begin{aligned}
& P^{\prime}=\frac{P}{(t-\zeta)(t-\bar{\zeta})\left(t^{-1}-\zeta\right)\left(t^{-1}-\bar{\zeta}\right)} \\
& P^{\prime}=g^{\prime} \bar{g}
\end{aligned}
$$

We set $g=g^{\prime}(t-\zeta)(t-\bar{\zeta})$ and $P=g \bar{g}$. Suppose $\zeta \in S^{1}$. Then $(t-\zeta)^{2} \mid P$ (at least - otherwise it would change sign). Therefore:

$$
\begin{aligned}
& P^{\prime}=\frac{P}{(t-\zeta)^{2}\left(t^{-1}-\zeta\right)^{2}} \\
& g=(t-\zeta)\left(t^{-1}-\zeta\right) g^{\prime} \quad \text { etc. }
\end{aligned}
$$

The map $(1,1) \mapsto \frac{h}{p^{k}}=\frac{g \bar{g} h}{p^{k}}$ is isometric whenever $g$ is coprime with $P$.

## Lemma 8.2

Suppose $A$ and $B$ are two symmetric polynomials that are coprime and that $\forall z \in S^{1}$ either $A(z)>0$ or $B(z)>0$. Then there exist symmetric polynomials $P, Q$ such that $P(z), Q(z)>0$ for $z \in S^{1}$ and $P A+Q B \equiv 1$.

Idea of proof. For any $z$ find an interval $\left(a_{z}, b_{z}\right)$ such that if $P(z) \in\left(a_{z}, b_{z}\right)$ and $P(z) A(z)+Q(z) B(z)=1$, then $Q(z)>0, x(z)=\frac{a z+b z}{i}$ is a continues function on $S^{1}$ approximating $z$ by a polynomial. ??????????????????????????

$$
\begin{array}{r}
(1,1) \mapsto \frac{h}{p^{k}} \mapsto \frac{g \bar{g} h}{p^{k}} \\
g \bar{g} h+p^{k} \omega=1
\end{array}
$$

Apply Lemma 8.2 for $A=h, B=p^{2 k}$. Then, if the assumptions are satisfied,

$$
\begin{array}{r}
P h+Q p^{2 k}=1 \\
p>0 \Rightarrow p=g \bar{g} \\
p=(t-\xi)(t-\bar{\xi}) t^{-1} \\
\text { so } p \geq 0 \text { on } S^{1} \\
p(t)=0 \Leftrightarrow t=\xi \text { ort }=\bar{\xi} \\
h(\xi)>0 \\
h(\bar{\xi})>0 \\
g \bar{g} h+Q p^{2 k}=1 \\
g \bar{g} h \equiv 1 \quad \bmod p^{2 k} \\
g \bar{g} \equiv 1 \quad \bmod p^{k}
\end{array}
$$

???????????????????????????????
If $P$ has no roots on $S^{1}$ then $B(z)>0$ for all $z$, so the assumptions of Lemma 8.2 are satisfied no matter what $A$ is.
?????????????????

$$
\begin{aligned}
& \left(\Lambda / p_{\xi}^{k} \times \Lambda / p_{\xi}^{k}\right) \longrightarrow \frac{\epsilon}{p_{\xi}^{k}}, \quad \xi \in S^{1} \backslash\{ \pm 1\} \\
& \left(\Lambda / q_{\xi}^{k} \times \Lambda / q_{\xi}^{k}\right) \longrightarrow \frac{1}{q_{\xi}^{k}}, \quad \xi \notin S^{1}
\end{aligned}
$$

???????????????????? 1 ?? epsilon?

## Theorem 8.2

(Matumoto, Conway-Borodzik-Politarczyk) Let $K$ be a knot,

$$
\begin{gathered}
H_{1}(\widetilde{X}, \Lambda) \times H_{1}(\widetilde{X}, \Lambda)=\bigoplus_{\substack{k, \xi, \epsilon \\
\xi i n S^{1}}}\left(\Lambda / p_{\xi}^{k}, \epsilon\right)^{n_{k}, \xi, \epsilon} \oplus \bigoplus_{k, \eta}\left(\Lambda / p_{\xi}^{k}\right)^{m_{k}} \\
\text { Let } \delta_{\sigma}(\xi)=\lim _{\varepsilon \rightarrow 0^{+}} \sigma\left(e^{2 \pi i \varepsilon} \xi\right)-\sigma\left(e^{-2 \pi i \varepsilon} \xi\right), \\
\text { then } \sigma_{j}(\xi)=\sigma(\xi)-\frac{1}{2} \lim _{\varepsilon \rightarrow 0} \sigma\left(e^{2 \pi i \varepsilon} \xi\right)+\sigma\left(e^{-2 \pi i \varepsilon} \xi\right)
\end{gathered}
$$

The jump at $\xi$ is equal to $2 \sum_{k_{i} \text { odd }} \epsilon_{i}$. The peak of the signature function is equal to $\sum_{k_{i} \text { even }} \epsilon_{i}$.

## Lecture 9

May 27, 2019

## Definition 9.1

A square hermitian matrix $A$ of size $n$.
field of fractions

Lecture 10
June 3, 2019

## Theorem 10.1

Let $K$ be a knot and $u(K)$ its unknotting number. Let $g_{4}(K)$ be a minimal four genus of a smooth surface $S$ in $B^{4}$ such that $\partial S=K$. Then:

$$
u(K) \geq g_{4}(K)
$$

Proof. Recall that if $u(K)=u$ then $K$ bounds a disk $\Delta$ with $u$ ordinary double points.
Remove from $\Delta$ the two self intersecting and glue the Seifert surface for the Hopf link. The reality surface $S$ has Euler characteristic $\chi(S)=1-2 u$. Therefore $g_{4}(S)=u$.

## ???????????????????

## Example 10.1

The knot $8_{20}$ is slice: $\sigma \equiv 0$ almost everywhere but $\sigma\left(e^{\frac{2 \pi i}{6}}\right)=+1$.

## Surgery

Recall that $H_{1}\left(S^{1} \times S^{1}, \mathbb{Z}\right)=\mathbb{Z}^{3}$. As generators for $H_{1}$ we can set $\alpha=\left[S^{1} \times\{\mathrm{pt}\}\right]$ and $\beta=\left[\{\mathrm{pt}\} \times S^{1}\right]$. Suppose $\phi: S^{1} \times S^{1} \longrightarrow S^{1} \times S^{1}$ is a diffeomorphism. Consider an induced map on homology group:

$$
\begin{array}{rlrl}
H_{1}\left(S^{1} \times S^{1}, \mathbb{Z}\right) \ni \phi_{*}(\alpha) & =p \alpha+q \beta, & & p, q \in \mathbb{Z}, \\
\phi_{*}(\beta) & =r \alpha+s \beta, & r, s \in \mathbb{Z}, \\
\phi_{*} & =\left(\begin{array}{ll}
p & q \\
r & s
\end{array}\right) &
\end{array}
$$

As $\phi_{*}$ is diffeomorphis, it must be invertible over $\mathbb{Z}$. Then for a direction preserving diffeomorphism we have $\operatorname{det} \phi_{*}=1$. Therefore $\phi_{*} \in \operatorname{SL}(2, \mathbb{Z})$.

## Theorem 10.2

Every such a matrix can be realized as a torus.
Proof. (I) Geometric reason

$$
\begin{aligned}
\phi_{t}: S^{1} \times S^{1} & \longrightarrow S^{1} \times S^{1} \\
S^{1} \times\{\mathrm{pt}\} & \longrightarrow\{\mathrm{pt}\} \times S^{1} \\
\{\mathrm{pt}\} \times S^{1} & \longrightarrow S^{1} \times\{\mathrm{pt}\} \\
(x, y) & \mapsto(-y, x)
\end{aligned}
$$

## Lecture 11 balagan

Proof. By Poincaré duality we know that:

$$
\begin{aligned}
H_{3}(\Omega, Y) & \cong H^{0}(\Omega), \\
H_{2}(Y) & \cong H^{0}(Y), \\
H_{2}(\Omega) & \cong H^{1}(\Omega, Y), \\
H_{2}(\Omega, Y) & \cong H^{1}(\Omega) .
\end{aligned}
$$

Therefore $\operatorname{dim}_{\mathbb{Q}} H_{1}(Y) / V=\operatorname{dim}_{\mathbb{Q}} V$.
Suppose $g(K)=0$ ( $K$ is slice). Then $H_{1}(\Sigma, \mathbb{Z}) \cong H_{1}(Y, \mathbb{Z})$. Let $g_{\Sigma}$ be the genus of $\Sigma, \operatorname{dim} H_{1}(Y, \mathbb{Z})=2 g_{\Sigma}$. Then the Seifert form $V$ on a 4 manifolds???
?????
has a subspace of dimension $g_{\Sigma}$ on which it is zero:

$$
V=g_{\Sigma}\left\{\left(\begin{array}{cccccc}
\overbrace{0} & \ldots & 0 & * & \ldots & * \\
\vdots & & \vdots & \vdots & & \vdots \\
0 & \ldots & 0 & * & \ldots & * \\
* & \ldots & * & * & \ldots & * \\
\vdots & & \vdots & \vdots & & \vdots \\
* & \ldots & * & * & \ldots & *
\end{array}\right)_{2 g_{\Sigma} \times 2 g_{\Sigma}}\right.
$$

May 6, 2019

## Definition 12.1

Let $X$ be a knot complement. Then $H_{1}(X, \mathbb{Z}) \cong \mathbb{Z}$ and there exists an epimorphism $\pi_{1}(X) \xrightarrow{\phi} \mathbb{Z}$.
The infinite cyclic cover of a knot complement $X$ is the cover associated with the epimorphism $\phi$.

$$
\widetilde{X} \longrightarrow X
$$

Formal sums $\sum \phi_{i}(t) a_{i}+\sum \phi_{j}(t) \alpha_{j}$
finitely generated as a $\mathbb{Z}\left[t, t^{-1}\right]$ module.
Let $v_{i j}=\operatorname{lk}\left(a_{i}, a_{j}^{+}\right)$. Then $V=\left\{v_{i} j\right\}_{i, j=1}^{n}$ is the Seifert matrix associated to the surface $\Sigma$ and the basis $a_{1}, \ldots, a_{n}$. Therefore $a_{k}^{+}=\sum_{j} v_{j k} \alpha_{j}$. Then $\operatorname{lk}\left(a_{i}, a_{k}^{+}\right)=\operatorname{lk}\left(a_{k}^{+}, a_{i}\right)=\sum_{j} v_{j k} \operatorname{lk}\left(\alpha_{j}, a_{i}\right)=v_{i k}$. We also notice that $\operatorname{lk}\left(a_{i}, a_{j}^{-}\right)=\operatorname{lk}\left(a_{i}^{+}, a_{j}\right)=v_{i j}$ and $a_{j}^{-}=\sum_{k} v_{k j} t^{-1} \alpha_{j}$. The homology of $\widetilde{X}$ is generated by $a_{1}, \ldots, a_{n}$ and relations.

## Definition 12.2

The $\mathbb{Z}\left[t, t^{-1}\right]$ module $H_{1}(\widetilde{X})$ is called the Alexander module of knot $K$.


Figure 7: Infinite cyclic cover of a knot complement.

Let $R$ be a PID, $M$ a finitely generated $R$ module. Let us consider

$$
R^{k} \xrightarrow{A} R^{n} \longrightarrow M,
$$

where $A$ is a $k \times n$ matrix, assume $k \geq n$. The order of $M$ is the gcd of all determinants of the $n \times n$ minors of $A$. If $k=n$ then $\operatorname{ord} M=\operatorname{det} A$.

## Theorem 12.1

Order of $M$ doesn't depend on $A$.
For knots the order of the Alexander module is the Alexander polynomial.

## Theorem 12.2

$$
\forall x \in M:(\operatorname{ord} M) x=0
$$

$M$ is well defined up to a unit in $R$.

## Blanchfield pairing

## Lecture 13 balagan

## Theorem 13.1

Let $H_{p}$ be a p-torsion part of $H$. There exists an orthogonal decomposition of $H_{p}$ :

$$
H_{p}=H_{p, 1} \oplus \cdots \oplus H_{p, r_{p}}
$$



Figure 8: A knot complement.
$H_{p, i}$ is a cyclic module:

$$
H_{p, i}=\mathbb{Z}\left[t, t^{-1}\right] / p^{k_{i}} \mathbb{Z}\left[t, t^{-1}\right]
$$

The proof is the same as over $\mathbb{Z}$.

