

Interaction matrix

$$R = [r_{ui}] = \begin{bmatrix} \dots & \dots & \dots \\ \dots & r_{ui} & \dots \\ \dots & \dots & \dots \end{bmatrix}$$

m

n

$$R \in \mathbb{M}_{m \times n}$$

m users
 n items

User vectors (rows)

e.g. $r_u = [0, 1, 1, 0, 0, \dots]$

n

Item vectors (columns)

$$r_i = [1, 0, 0, 0, 1, \dots]$$

m

General model

$$\hat{r}_{ui} = f(r_u, r_i | \theta)$$

f - function dependent on parameters θ which has to be fit to data so that

$$\text{error} = \sum_u \sum_i d(r_{ui}, \hat{r}_{ui})$$

is minimized

Most often used distance is $d(r_{ui}, \hat{r}_{ui}) = (r_{ui} - \hat{r}_{ui})^2$

Problem

p_u and q_i are very long and sparse (contain mostly zeros)

Solution

Solution

Reduce dimensionality of user and item representation

$$r_u \in \mathbb{R}^n \rightarrow p_u \in \mathbb{R}^d \quad r_i \in \mathbb{R}^m \rightarrow q_i \in \mathbb{R}^d$$

How to do that?

- Dimensionality reduction (PCA, tSNE)
- Matrix factorization

Matrix factorization

Theorem (Singular Value Decomposition)

For every matrix $R \in \mathbb{M}_{m \times n}$ there exist matrices $P \in \mathbb{M}_{m \times m}$, $\Sigma \in \mathbb{M}_{m \times n}$, $Q \in \mathbb{M}_{n \times n}$ such that

$$R = P \Sigma Q^T$$

and

- rows of P are orthonormal vectors of $R R^T$
- rows of Q are orthonormal vectors of $R^T R$
- Σ is diagonal and the diagonal consists of square roots of all eigenvalues of $R R^T$ (which are also eigenvalues of $R^T R$)

A pair of eigenvector v and eigenvalue λ for a matrix A satisfy the following equation

$$A v = \lambda v$$

$$\underbrace{m}_{\substack{\{ \\ \underbrace{\quad}_n \\ \}} \left[\begin{array}{c} r_{1i} \\ \vdots \\ r_{mi} \end{array} \right] = \underbrace{m}_{\substack{\{ \\ \underbrace{\quad}_m \\ \}} \left[\begin{array}{c} v_1 \\ \vdots \\ v_m \end{array} \right] \cdot \underbrace{m}_{\substack{\{ \\ \underbrace{\quad}_n \\ \}} \left[\begin{array}{ccc} e_1 & e_2 & 0 \\ 0 & \ddots & \ddots \end{array} \right] \cdot \underbrace{n}_{\substack{\{ \\ \underbrace{\quad}_n \\ \}} \left[\begin{array}{c} w_1 \\ \vdots \\ w_n \end{array} \right]^T$$

v_1, \dots, v_m form orthonormal basis of \mathbb{R}^m

w_1, \dots, w_n form orthonormal basis of \mathbb{R}^n

After changing notation to

$$\left[\begin{array}{c} \beta_1 \\ \vdots \\ \beta_m \end{array} \right] = \left[\begin{array}{c} v_1 \\ \vdots \\ v_m \end{array} \right] \left[\begin{array}{ccc} e_1 & e_2 & 0 \\ 0 & \ddots & \ddots \end{array} \right]$$

and

$$\left[\begin{array}{c} q_1 \\ \vdots \\ q_n \end{array} \right] = \left[\begin{array}{c} w_1 \\ \vdots \\ w_n \end{array} \right]$$

we have

$$\left[\begin{array}{c} r_{1i} \\ \vdots \\ r_{mi} \end{array} \right] = \left[\begin{array}{c} \beta_1 \\ \vdots \\ \beta_m \end{array} \right] \left[\begin{array}{c} q_1 \\ \vdots \\ q_n \end{array} \right]^T$$

$$= \begin{bmatrix} \beta_1 q_1 & \beta_1 q_2 & \dots & \beta_1 q_n \\ \beta_2 q_1 & \dots & \ddots & \vdots \\ \vdots & & \ddots & \vdots \\ \beta_m q_1 & \dots & \dots & \beta_m q_n \end{bmatrix}$$

$$\forall_{u,i} \quad r_{u,i} = p_u \cdot q_i$$

Problem $p_u \in \mathbb{R}^n$, $q_i \in \mathbb{R}^n$ where n is large

Solution Approximate matrix R with only d largest eigenvalues (remove all other rows and columns)

$$R \approx P_d \Sigma_d Q_d^T$$

where

$$P_d \in \mathbb{M}_{m \times d}, \quad \Sigma_d \in \mathbb{M}_{d \times d}, \quad Q_d \in \mathbb{M}_{n \times d}$$

Then

$$\forall_{u,i} \quad r_{u,i} \approx p_u \cdot q_i$$

and $p_u \in \mathbb{R}^d$, $q_i \in \mathbb{R}^d$

(the higher the value of d , the more accurate this approximation is; but typically relatively very small d is enough to obtain very high accuracy)

Idea for a recommender

Find dense representation vectors $p_u \in \mathbb{R}^d$, $q_i \in \mathbb{R}^d$ such that

$$MSE = \frac{1}{|R|} \sum_{u,i} (r_{u,i} - \hat{r}_{u,i})^2 = \frac{1}{|R|} \sum_{u,i} (r_{u,i} - p_u \cdot q_i)^2$$

is minimized.

Here $|R|$ is the number of interactions used for training.

Then our model is given by

$$\hat{r}_{u,i} = f(r_u, r_i) = p_u \cdot q_i$$

It can be proven that for $d=n$ minimizing the squared error as defined above yields exactly the same matrix decomposition as given by the Singular Value Decomposition theorem !

MSE error can be minimized using many methods:

- SGD (Stochastic Gradient Descent)
- ALS (Alternating Least Squares)
- black box optimizers, e.g. Tree Parzen Estimator